

## Jordan University of Science and Technology Faculty of Engineering Mechanical Engineering Department

ME784 Introduction To Robots - JNQF Level: 9

Second Semester 2023-2024

**Course Catalog** 

3 Credit Hours. 3 Credit hours (3 h lectures). Overview of the field of robotics and their applications; Types, locomotion, kinematics (forward and inverse), dynamics (forward and inverse), planning, control and design of manipulators and mobile robots; Robotics perception (sensors) and actuators; Multi-robotics systems.

Teaching Method: On Campus

| Text Book            |   |  |
|----------------------|---|--|
| Title                | Introduction to Robotics: Mechanics and Control |  |
| Author(s)            | John J. Craig                                   |  |
| Edition              | 3rd Edition                                     |  |
| Short Name           | TextBook  |  |
| Other<br>Information | Pearson Prentice Hall, ISBN: 0-201-54361-3      |  |

| Instructor      |                     |  |
|-----------------|---------------------|--|
| Name            | Dr. Khaled Hatamleh |  |
| Office Location | N1_L2               |  |
| Office Hours    |                     |  |
| Email           | kshh@just.edu.jo    |  |

**Class Schedule & Room** 

Section 3: Lecture Time: Thu : 14:30 - 17:30 Room: LAB

## **Tentative List of Topics Covered**

| Weeks        | Торіс  | References |
|--------------|--|------------|
| Weeks 1, 2   | Spatial descriptions and transformations. (CH. 1and 2) |            |
| Weeks 3, 4   | Manipulator Kinematics. (CH. 3)                        |            |
| Weeks 5, 6   | Inverse manipulator kinematics. (CH. 4)                |            |
| Weeks 7, 8   | Jacobians: velocities and static forces. (CH. 5)       |            |
| Weeks 9, 10  | Manipulator dynamics. (CH. 6)                          |            |
| Weeks 12, 13 | Trajectory generation. (CH. 7)                         |            |

| Mapping of Course Outcomes to Program Outcomes and NQF Outcomes   | Course Outcome<br>Weight (Out of<br>100%) | Assessment<br>method |
|---|---|----------------------|
| Analyze the kinematic and dynamic models of robotic manipulators to determine operational performance and identify potential limitations. [1L9S3]                     | 25%                                       |                      |
| Evaluate the effectiveness of various trajectory generation techniques for achieving precise motion control in robotic systems. [1L9K2]                               | 25%                                       |                      |
| Assess the impact of Jacobians on the performance of robotic manipulators, particularly in terms of velocities and static forces under real-world conditions. [1L9C6] | 25%                                       |                      |
| Design and simulate robotic manipulator trajectories using MATLAB to achieve optimized motion for complex tasks. [1L9C4]  | 25%                                       |                      |

|      | Relationship to NQF C | Outcomes (Out of 100%) |      |
|------|-----------------------|------------------------|------|
| L9K2 | L9C4                  | L9S3                   | L9C6 |
| 25   | 25                    | 25                     | 25   |

| Policy   |  |  |
|----------|--|--|
| Policies | <ol> <li>Please turn off your cell phones at all times during the class; if your cell phone causes any disturbance<br/>during the class, backup your belongings and leave calmly. If you do not leave, your participation grade may<br/>reduce severely.</li> <li>Please turn back your HW on time, Late HW is acceptable with a 20% penalty for every late calendar day<br/>(including weekends).</li> <li>Never be ashamed to ask.</li> <li>If the office hours are not suitable for you, we can arrange a meeting time through e-mail.</li> <li>For any reason, and when you cannot contact me physically, you can use the e-mail.</li> <li>Make up exams will not be held without an official excuse.</li> </ol> |  |

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